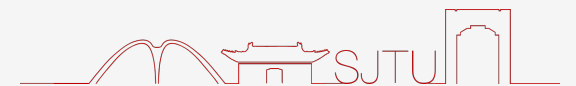


# **MuDiS: An Audio-independent, Wide-angle, and Leak-free Multi-directional Speaker**

MobiCom 2024



# Directional Speaker Applications



Museum



Gym

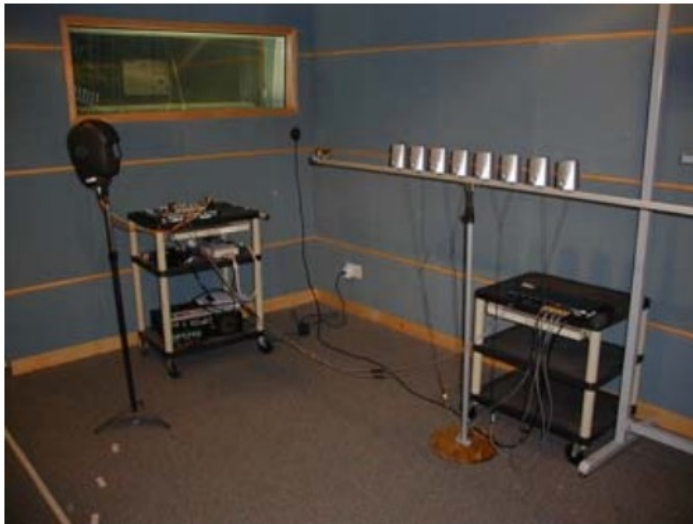


Advertisements

**Directional speakers can direct sound waves **only to specific areas,** which can create customized sound zones for individuals**



## Existing Solutions – Speaker Phased Array



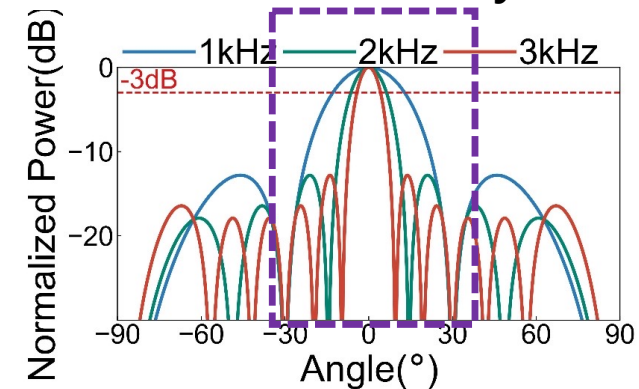
Conventional Speaker Phased Array



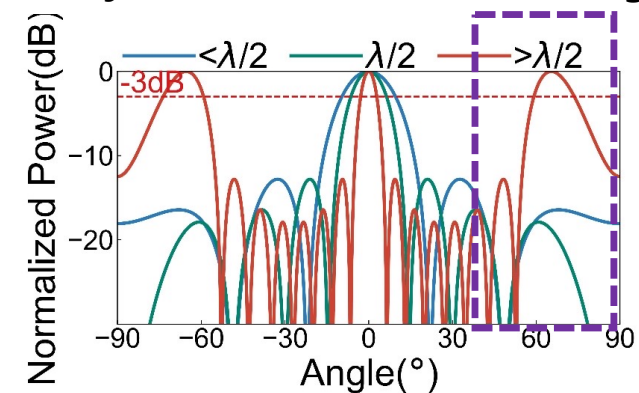
JBL Intellivox DS115



### Poor Consistency



### Bulky to achieve half wavelength



# Parametric Array - Air Nonlinearity



## Air Nonlinearity

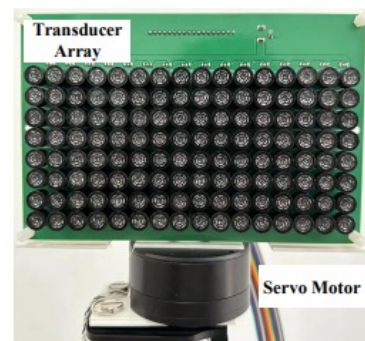
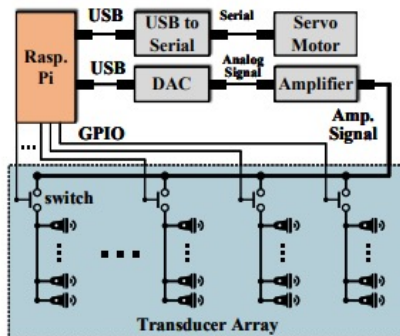
Primary High-Frequency Beam ( $f_1, f_2$ )

**Air Nonlinearity can reproduce audible sounds from ultrasound.**

**Air Nonlinearity**



**Phased Array**



- Compact Size
- Better consistency



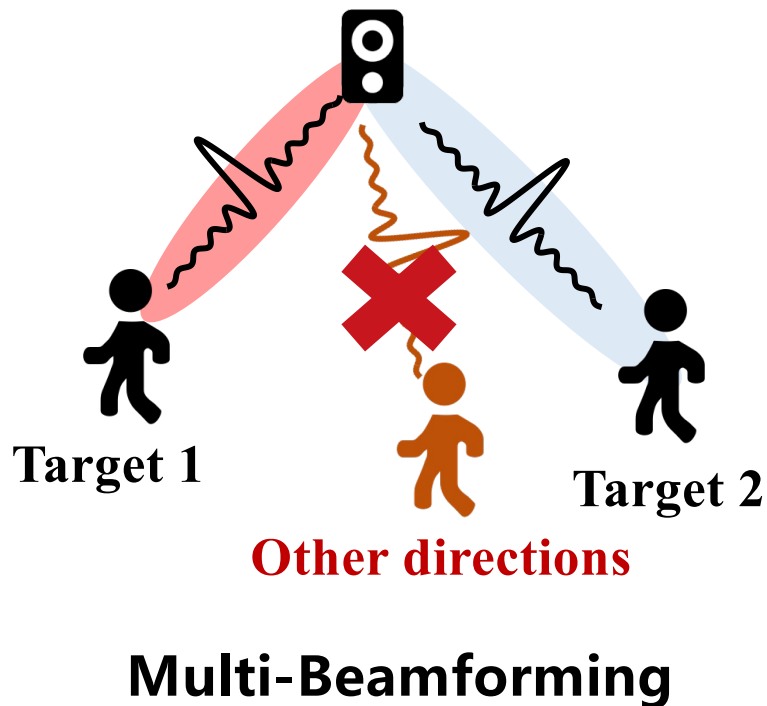
- Cannot support Multi-beam
- Mechanical steering



# MuDiS – Multi-Directional Speaker



## Multi-Directional Speaker



## Design Goal

### ➤ Independent Beams:

Diverse content must be concurrently delivered in distinct directions.

### ➤ Wide-angle Steering:

The beam must be dynamically adjustable to encompass a broad coverage

### ➤ Leakage suppression:

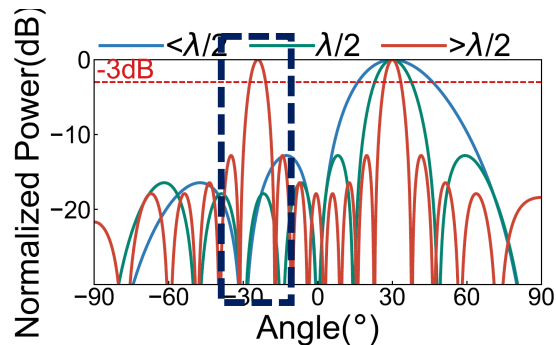
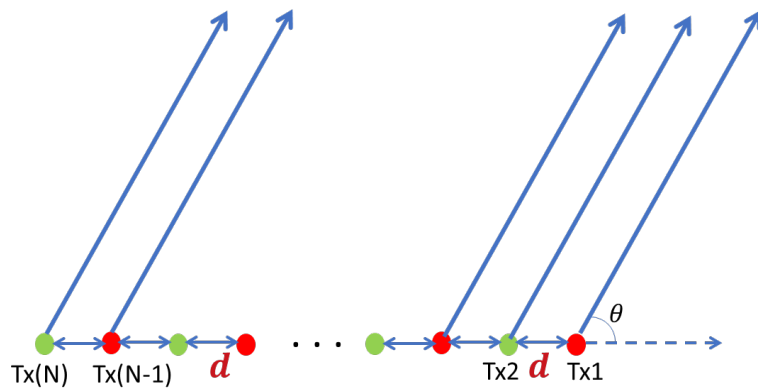
The sound should exclusively appear in the desired direction, preventing sound leakage in unintended directions.

- 1) **Physical Limitation** of Transducer
- 2) Additional **Leakage** due to Nonlinear Effect

# Challenge 1: Physical Limitations of Transducer

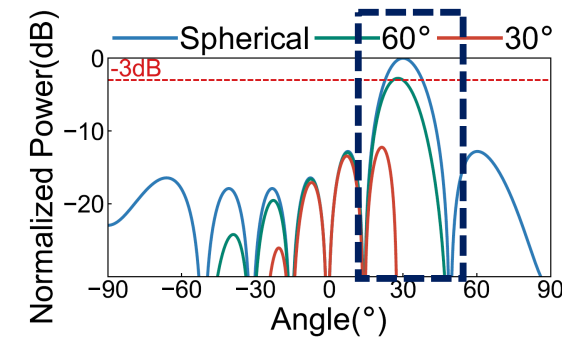
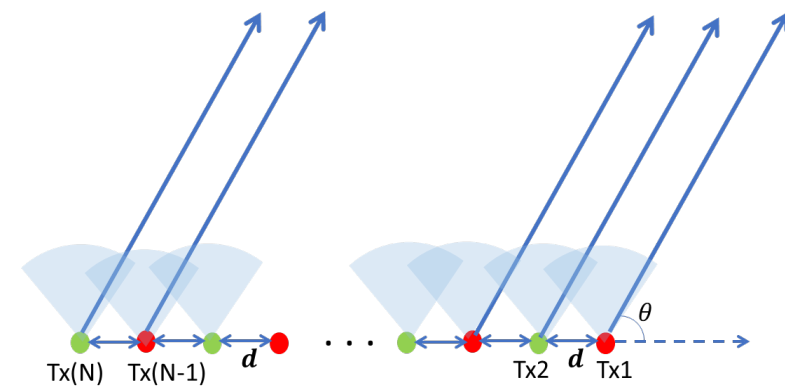


## Element Spacing $d > \lambda/2$



✖ Leakages by Grating Lobes

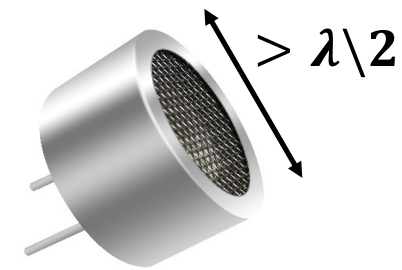
## Emitting Focusing Waves



✖ Limited Steering Angle



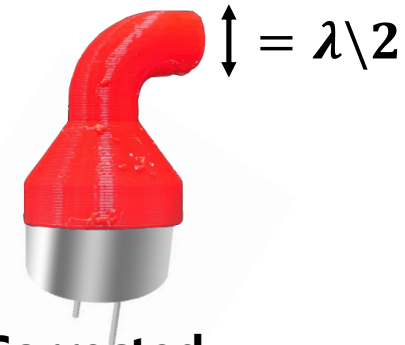
## Key idea – Design a 3D-printed Structure



Ultrasonic Transducer



3D-printed Structure



Corrected Spacing and wavefront

### Design Goal

- Correct Element Spacing to  $\lambda/2$
- Correct to approximate **spherical** wavefront
- **Maximize** the output energy

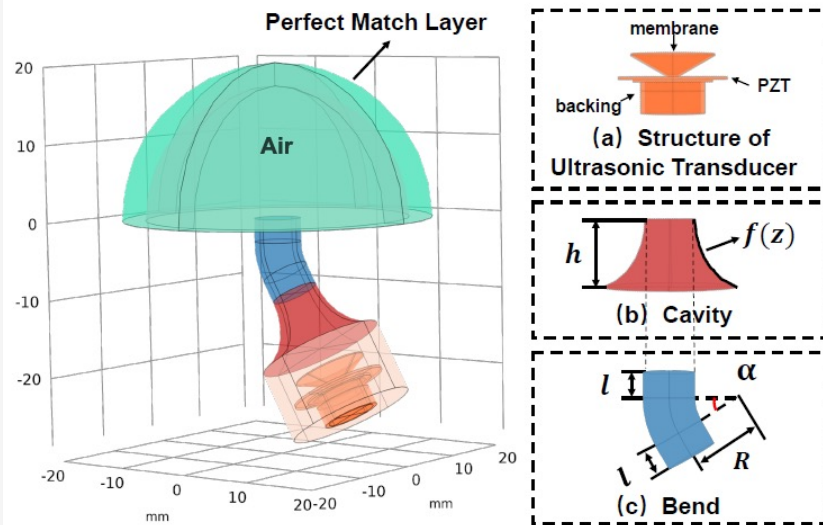




# Empirical Acoustic Metasurface Design

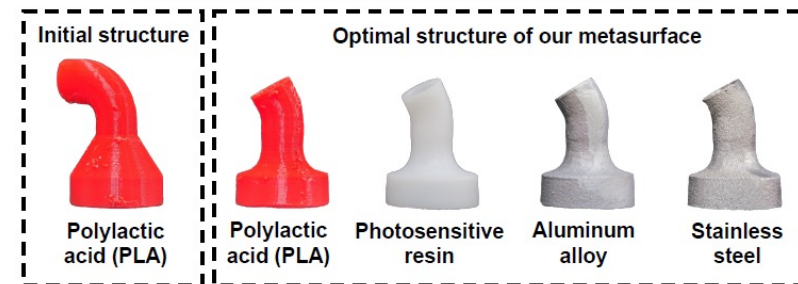


## Simulation in COMSOL

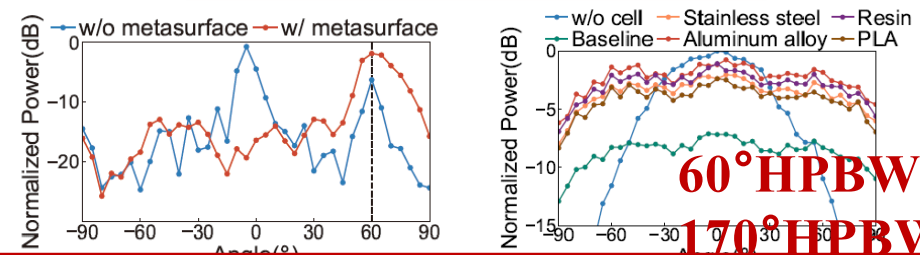


- Correct Element Spacing to  $\lambda/2$
- Correct to approximate spherical wavefront

## Optimal 3D Printed Cells



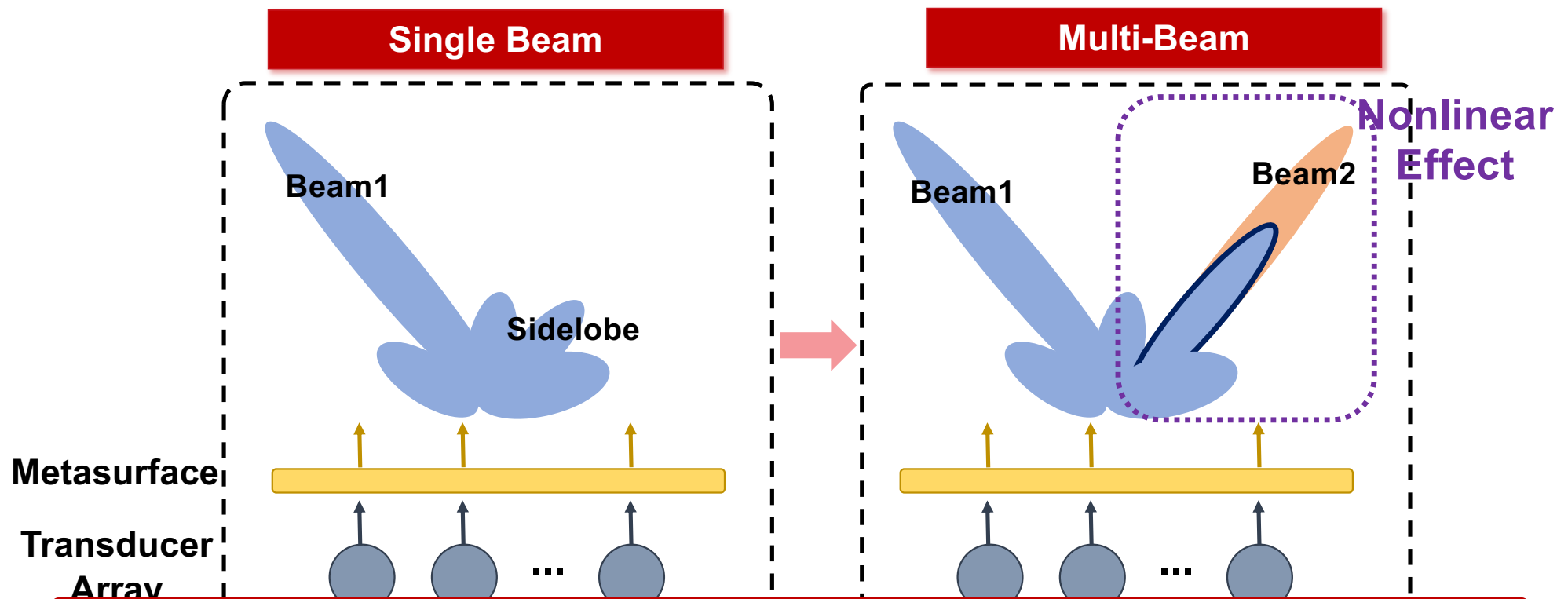
## Performance



Metasurface helps correct element spacing and output wavefront



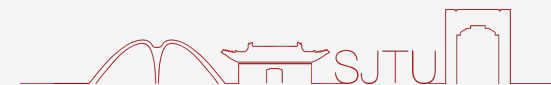
## Challenge 2: Leakage due to Nonlinear Effect



**Nonlinear Effect will introduce additional leakages**



## Challenge 2: Leakage due to Nonlinear Effect



Assume the original signal are  $h_1(t)$ ,  $h_2(t)$ , the modulated signal will be:

$$s_1(t) = h_1(t)\cos(2\pi f_c t) + \cos(2\pi f_c t)$$

$$s_2(t) = h_2(t)\cos(2\pi f_c t) + \cos(2\pi f_c t)$$

According to pre-set beam weights, when the target directions are  $\theta_1, \theta_2$ , the output signal will be  $s_1(t)w_{\theta_1} + s_2(t)w_{\theta_2}$

Then the received **high-frequency** signal in  $\theta_2$  is:

$$\begin{aligned} R_{High}^{Multi}(\theta_2) &= A \sum (s_1(t)w_{\theta_1} + s_2(t)w_{\theta_2}) e^{j2\pi \frac{d}{\lambda_i} (n-1) \sin \theta_2} \\ &= An(\alpha s_1(t)e^{j\sigma} + s_2(t)) \end{aligned}$$

Now the **audible sound** in  $\theta_2$  will be

$$\begin{aligned} R_{Low}^{Multi}(\theta_2) &= LPF \left( A_2 (R_{High}^{Multi}(\theta_2))^2 \right) \\ &= A_2 A^2 n^2 LPF \left[ \underbrace{s_2(t)^2}_{\text{Expected}} + \underbrace{2\alpha s_2(t)s_1(t)e^{j\sigma}}_{\text{Leakages}} + \underbrace{\alpha^2 (s_1(t)e^{j\sigma})^2}_{\text{Ignored}} \right] \end{aligned}$$

Expected

Leakages

Ignored



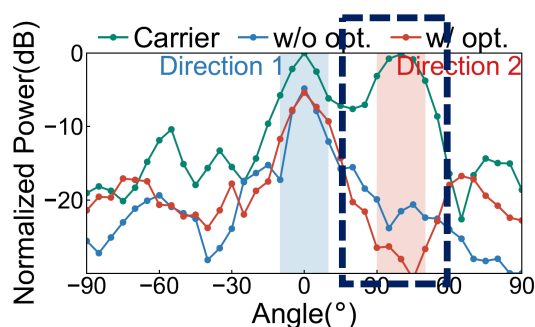
## Challenge 2: Leakage due to Nonlinear Effect



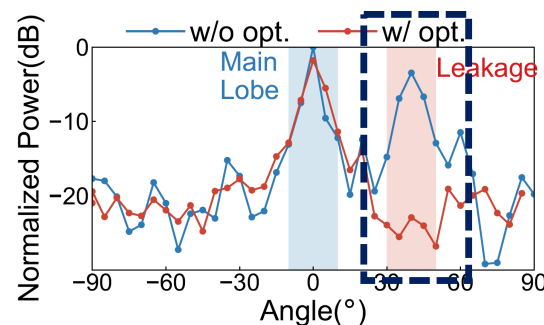
Assume the original signal are  $h_1(t)$ ,  $h_2(t)$ , the modulated signal will be:

$$s_1(t) = h_1(t)\cos(2\pi f_c t) + \cos(2\pi f_c t)$$

### Leakages in Unintended directions



High frequency beam pattern



Low frequency beam pattern

$$R_{Low}^{Multi}(\theta_2) = LPF \left( A_2 (R_{High}^{Multi}(\theta_2)^2) \right)$$

$$= A_2 A^2 n^2 LPF \left[ \underbrace{s_2(t)^2}_{\text{Expected}} + \underbrace{2\alpha s_2(t)s_1(t)e^{j\sigma}}_{\text{Leakages}} + \underbrace{\alpha^2 (s_1(t)e^{j\sigma})^2}_{\text{Ignored}} \right]$$

Expected

Leakages

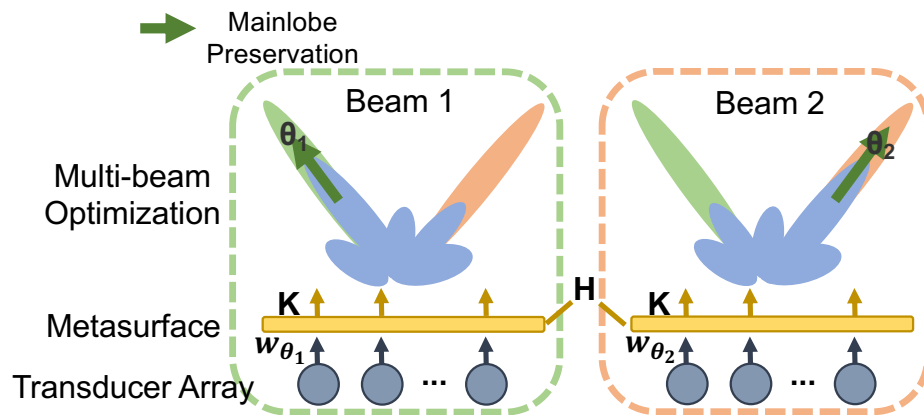
Ignored



# Optimization-based Beamforming



## Problem Formulation



### ■ Mainlobe preservation

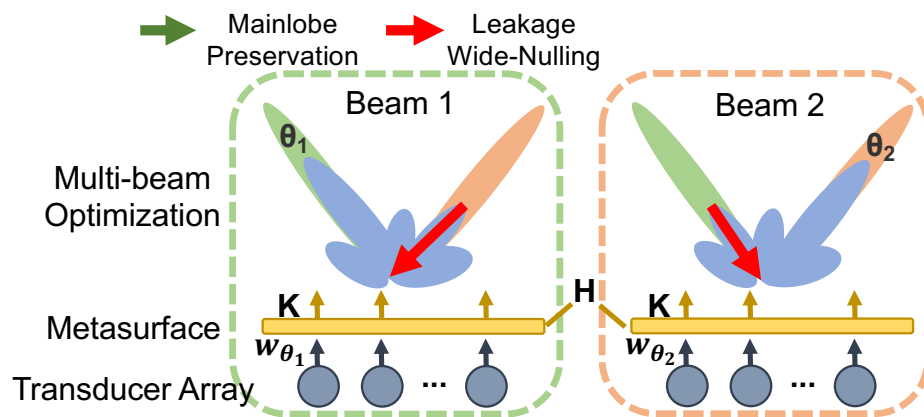
$$L_{main} = \sum P \times \text{mask}([\theta - \alpha, \theta + \alpha])$$



# Optimization-based Beamforming



## Problem Formulation



### ■ Mainlobe preservation

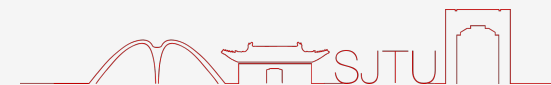
$$L_{main} = \sum P \times \text{mask}([\theta - \alpha, \theta + \alpha])$$

### ■ Leakage wide-nulling

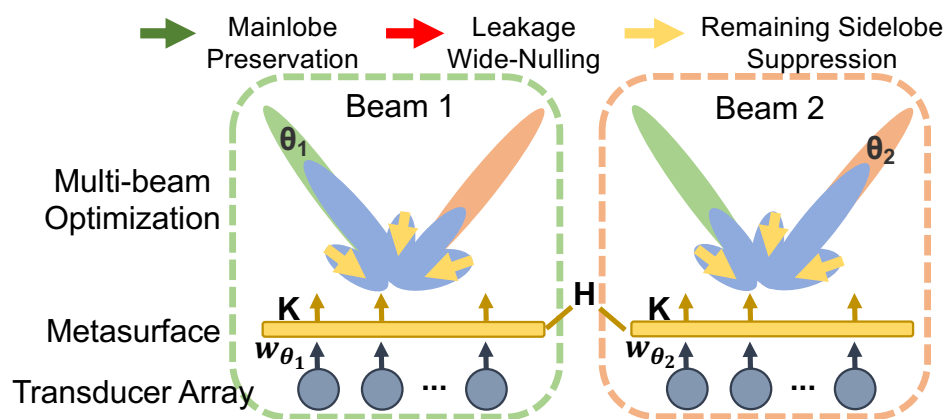
$$L_{null} = \sum P \times \text{mask}([\Theta_l - \beta, \Theta_l + \beta])$$



# Optimization-based Beamforming



## Problem Formulation



### ■ Mainlobe preservation

$$L_{main} = \sum P \times \text{mask}([\theta - \alpha, \theta + \alpha])$$

### ■ Leakage wide-nulling

$$L_{null} = \sum P \times \text{mask}([\Theta_l - \beta, \Theta_l + \beta])$$

### ■ Remain sidelobe suppression

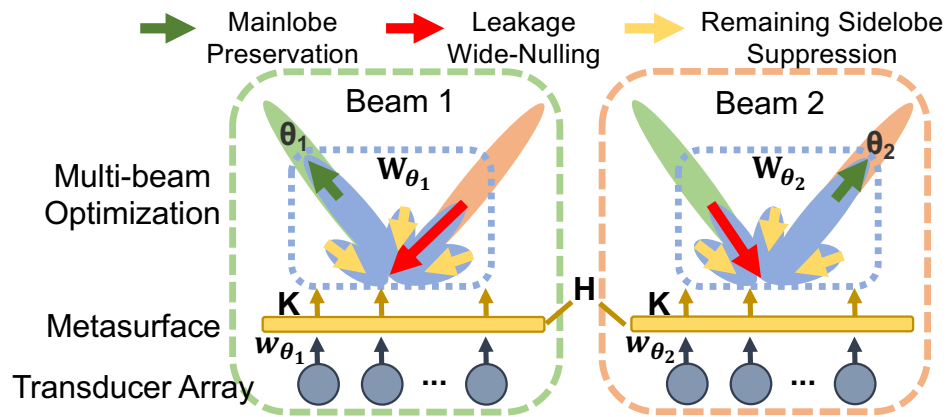
$$L_{remain} = \sum \text{peak}(P \times \text{mask}(\Theta_m))$$



# Optimization-based Beamforming



## Problem Formulation



### ■ Mainlobe preservation

$$L_{main} = \sum P \times \text{mask}([\theta - \alpha, \theta + \alpha])$$

### ■ Leakage wide-nulling

$$L_{null} = \sum P \times \text{mask}([\Theta_l - \beta, \Theta_l + \beta])$$

### ■ Remain sidelobe suppression

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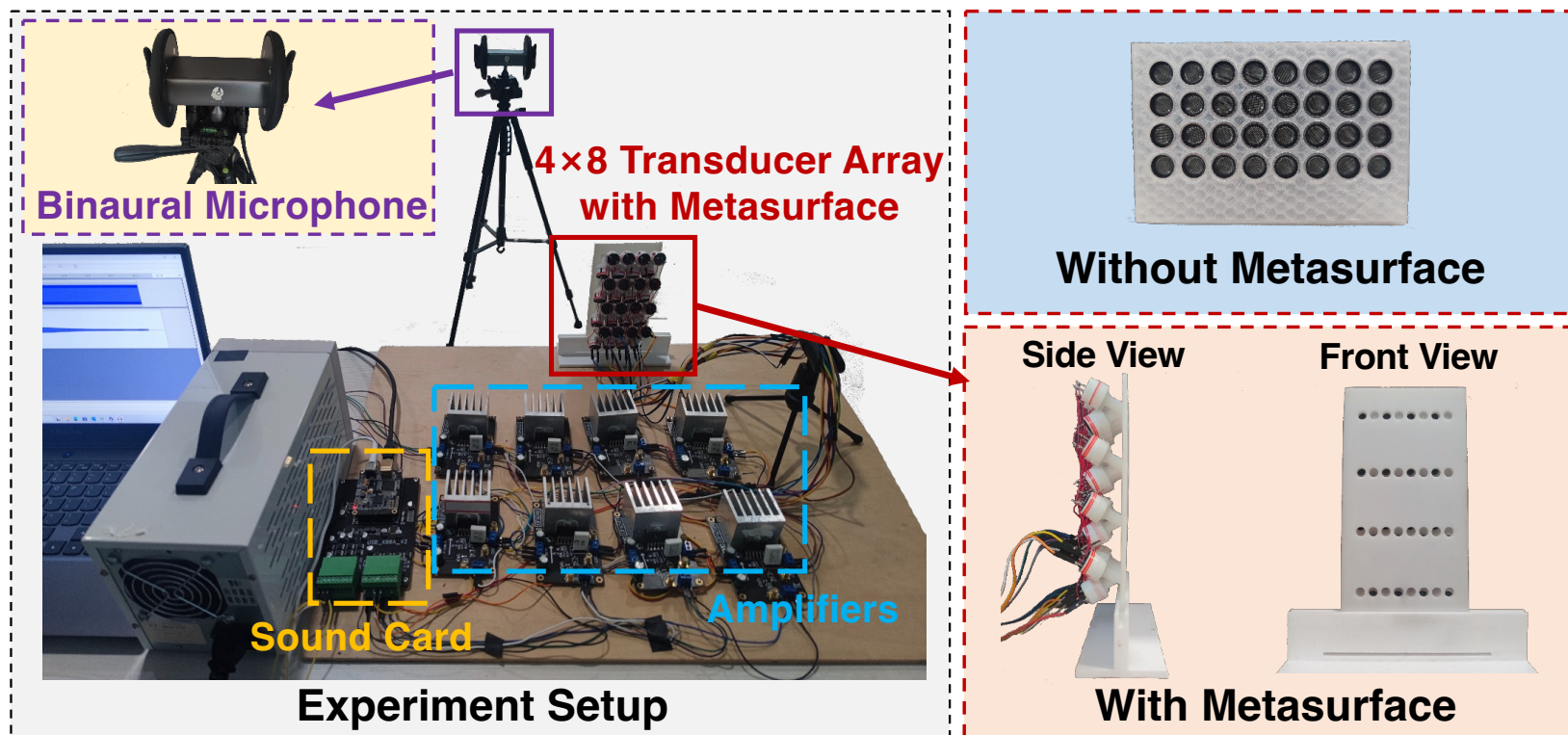
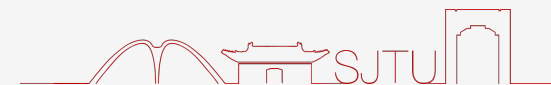
## Objective Function

$$\begin{aligned} \max_{\mathbf{w}_\theta} \quad & L_{main} - \delta L_{null} - \eta L_{remain} \\ \text{s.t.} \quad & |\mathbf{w}_\theta| \leq 1 \quad (\theta \in \Theta) \end{aligned}$$

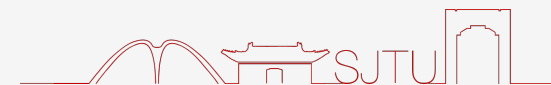




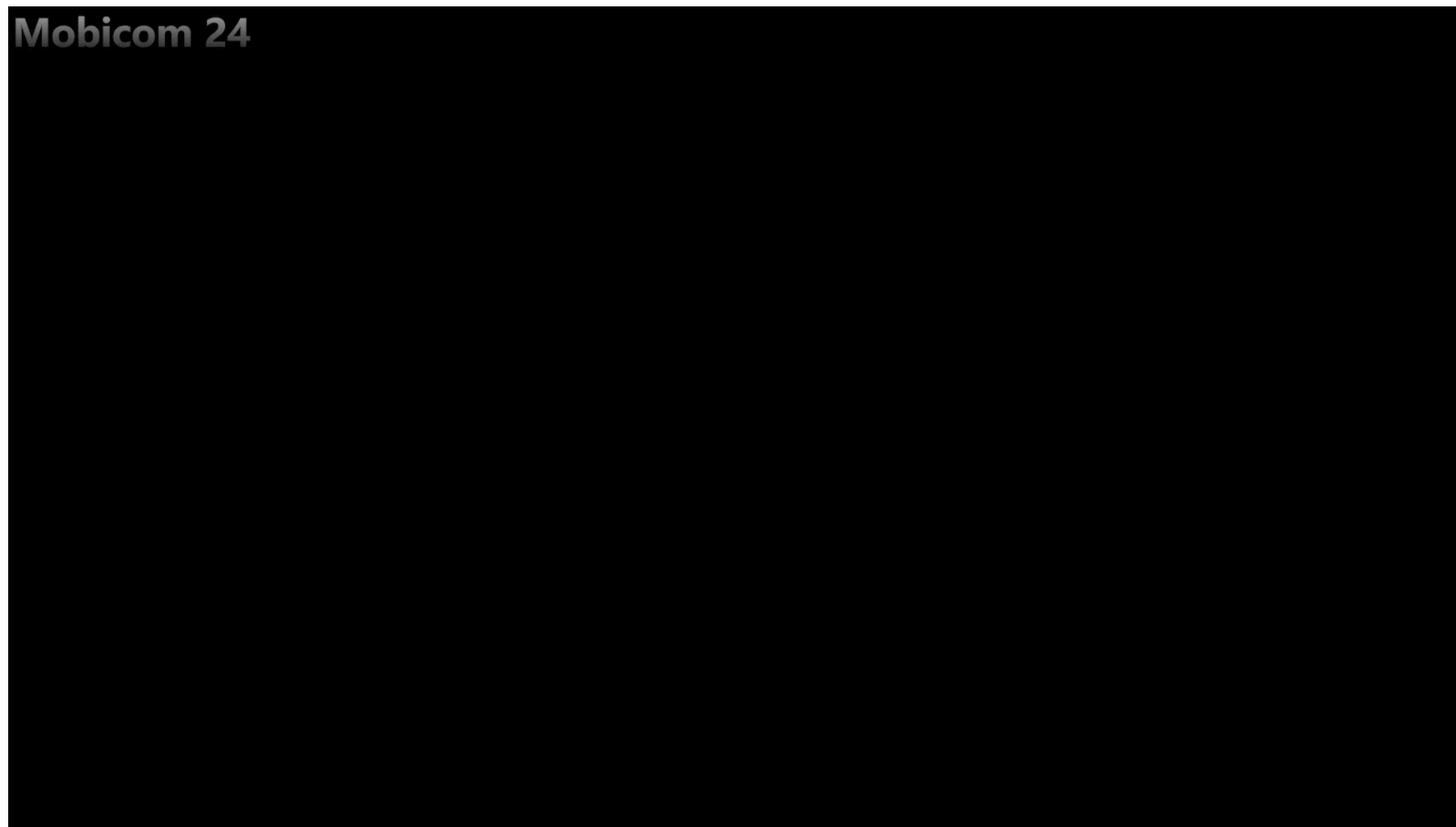
# Experiment Setup



# Demo



Mobicom 24



<https://acousticmudis.github.io/>



[Mobicom 24'] An Audio-independent, Wide-angle, and Leak-free Multi-directional Speaker

# Performance



**MCD:** Mel-cepstral Distance    **SWPR:** Signal-to-Worst-Point Ratio

**Table 1: The performance comparison of MuDiS under different schemes.**

		Beam Num.	Methods					Metrics			
			Beam-forming	Meta-surface	Leakage Cancellation	Phase Robust	Distortion Reduction	SNR	PESQ	MCD	SWPR
MuDiS	2-beams	2	✓	✓	✓	✓	✓	6.56	3.25	4.31	10.97
	3-beams	3	✓	✓	✓	✓	✓	5.85	2.88	5.26	8.62
	4-beams	4	✓	✓	✓	✓	✓	5.66	2.67	6.03	6.93
	1-beam	1	✓	✓	✗	✗	✓	6.96	3.42	4.14	18.95
COTS Directional Speaker		1	✓	-	-	-	-	6.07	3.40	4.70	15.37
Smartphone Speaker		-	✗	-	-	-	-	8.52	4.02	3.04	0.86

**The system can support 4 beams playing simultaneously**



# Performance



**MCD:** Mel-cepstral Distance    **SWPR:** Signal-to-Worst-Point Ratio

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	3-beams	3	✓	✓	✓	✓	✓	5.85	2.88	5.26	8.62
	4-beams	4	✓	✓	✓	✓	✓	5.66	2.67	6.03	6.93
	1-beam	1	✓	✓	✗	✗	✓	6.96	3.42	4.14	18.95
COTS Directional Speaker		1	✓	-	-	-	-	6.07	3.40	4.70	15.37
Smartphone Speaker		-	✗	-	-	-	-	8.52	4.02	3.04	0.86

**Close Performance to COTS directional speaker when playing multiple beams**



## Conclusion



- Implemented a **multi-directional speaker**, facilitating **broad angles** for delivering diverse audio content along various directions
- Designed a metasurface to **overcome physical limitation** of ultrasonic transducers
- Proposed an optimization-based beamforming scheme to **suppress unintended leakages**



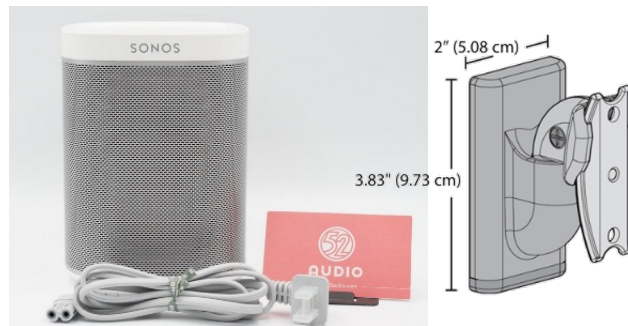


上海交通大學  
SHANGHAI JIAO TONG UNIVERSITY

**Thank You**

飲水思源 愛國榮校

## Other COTS Directional Speaker



**Sonos Play + RocketFish Mount**

**✗ Mechanical Steering**



**SXS Multi Directional Audio Pods**

**✗ Limited Steering Angle (forward and back)**



**PAN Acoustics**

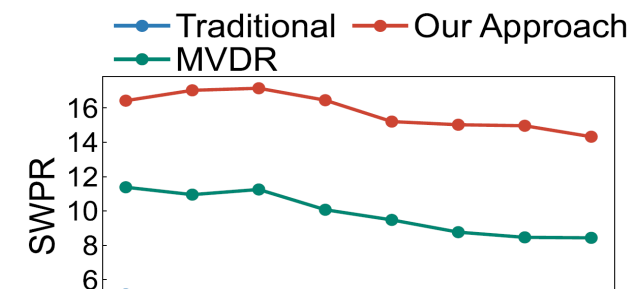
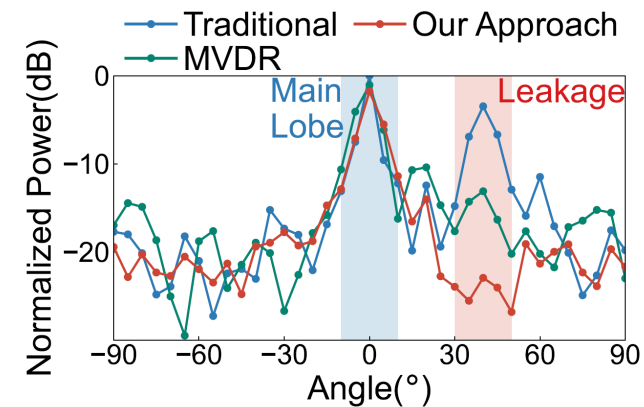
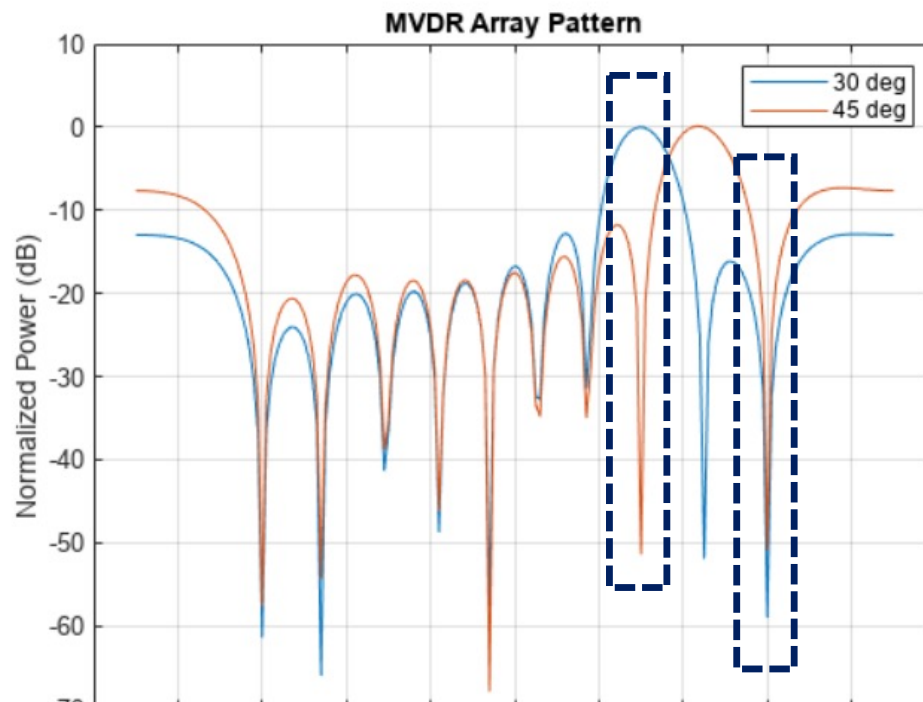
**✗ Identical Audio Beams**



# Minimum Variance Distortionless Response



## Minimum Variance Distortionless Response (MVDR)



**MVDR can only suppress one angle point, thus the performance is worse**





➤ **SNR:** Signal-to-Noise Ratio

$$SNR(x, \hat{x}) = 10 \log_{10} \left( \frac{\|x\|_2^2}{\|x - \hat{x}\|_2^2} \right)$$

➤ **PESQ:** Perceptual evaluation of speech quality

assess speech quality and generate a score ranging from -0.5 to 4.5, which is based on a psychoacoustic model that simulates human auditory system's response

➤ **MCD:** Mel-cepstral Distance

measures the similarity between sounds accounting for the ear's critical bandwidth as a function of frequency

➤ **SWPR:** Signal-to-Worst-Point Ratio

assess the maximum interference in other directions apart from the intended one. It is defined as the difference between the peak of the main lobe and the peak in other directions.

# Overall Performance



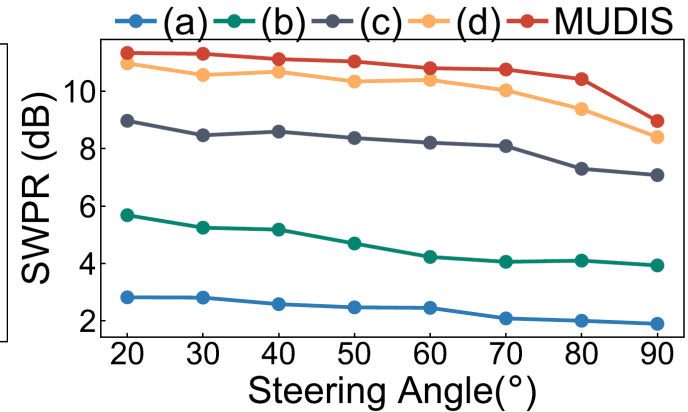
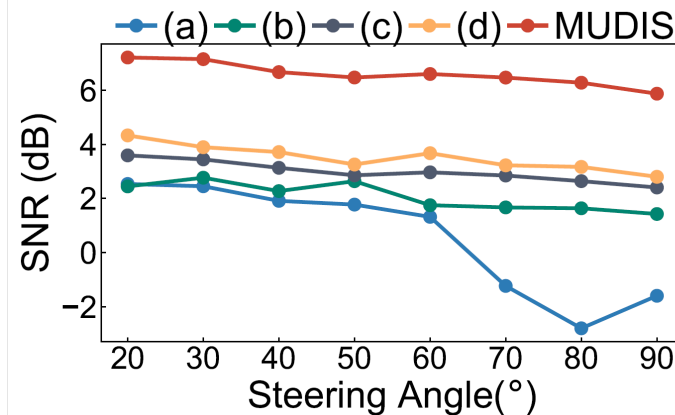
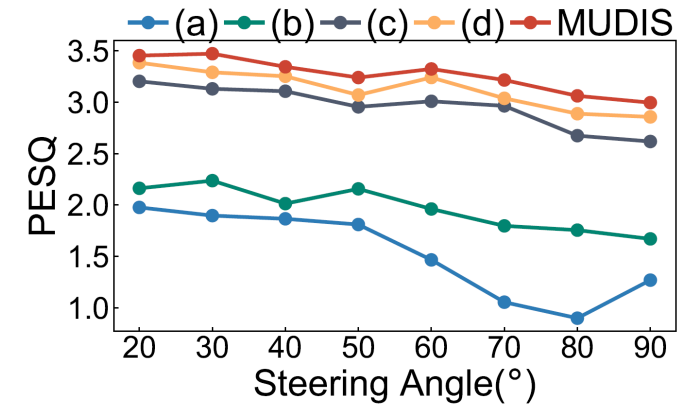
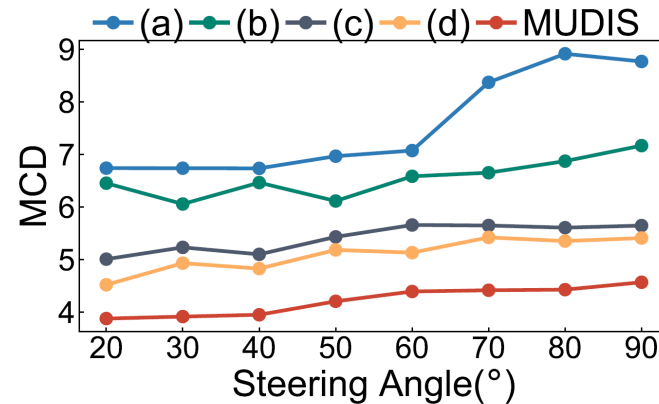
(a) Traditional beamforming

(b) Traditional beamforming + Metasurface

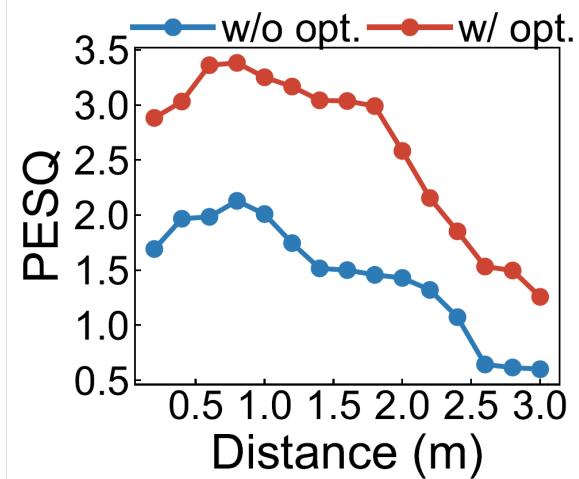
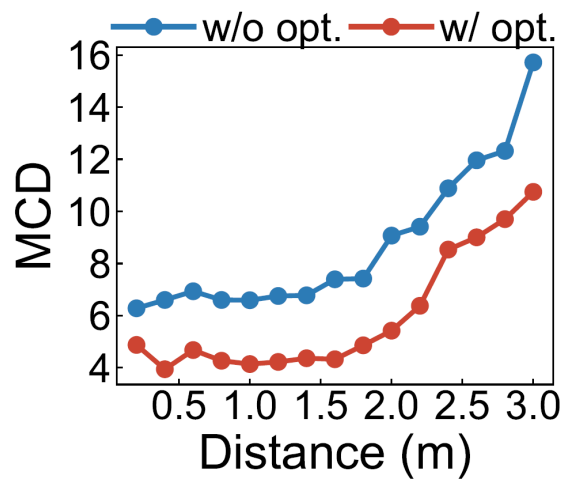
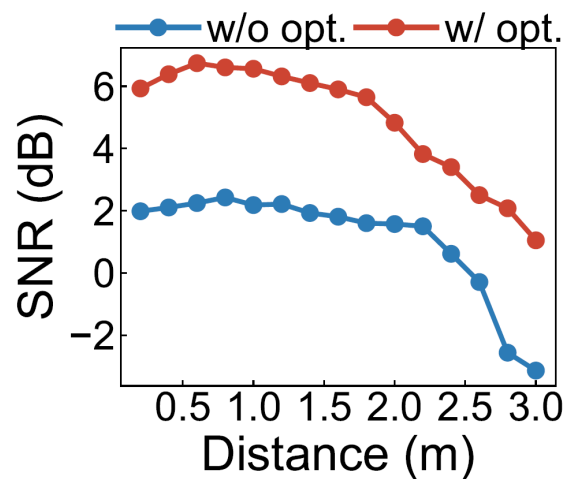
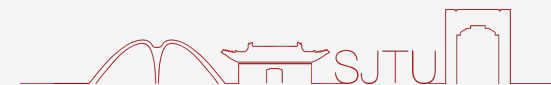
(c) Traditional beamforming + Metasurface + Optimization

(d) Traditional beamforming + Metasurface + Optimization + Phase Robust

(e) MUDIS: Traditional beamforming + Metasurface + Optimization + Phase Robust + Distortion Reduction



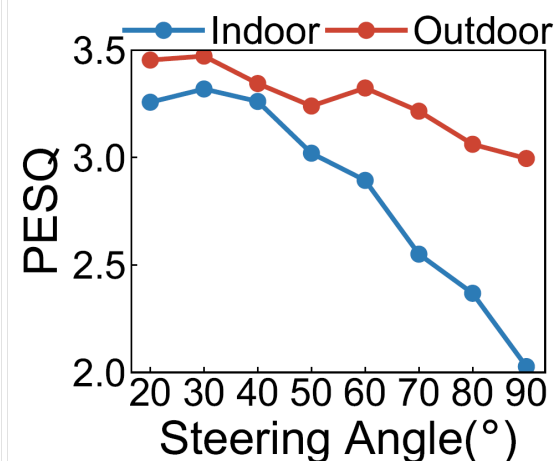
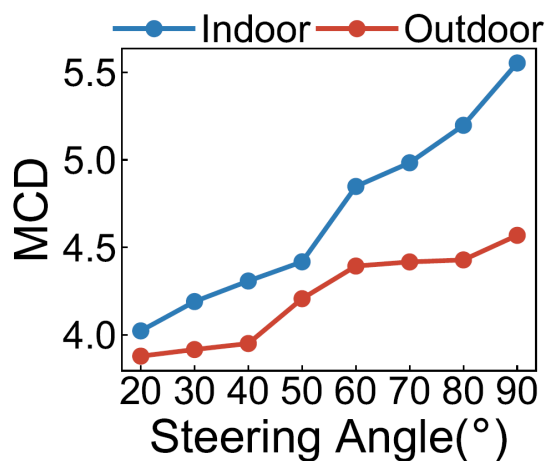
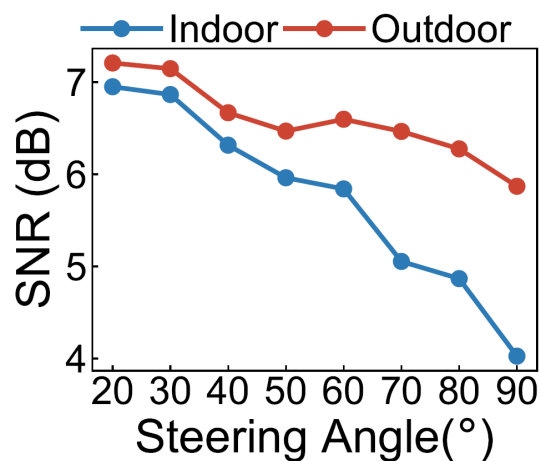
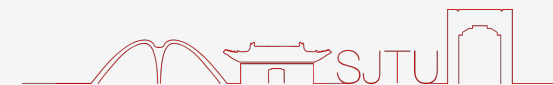
## Impact of distance



**Our system can support 2m distance**



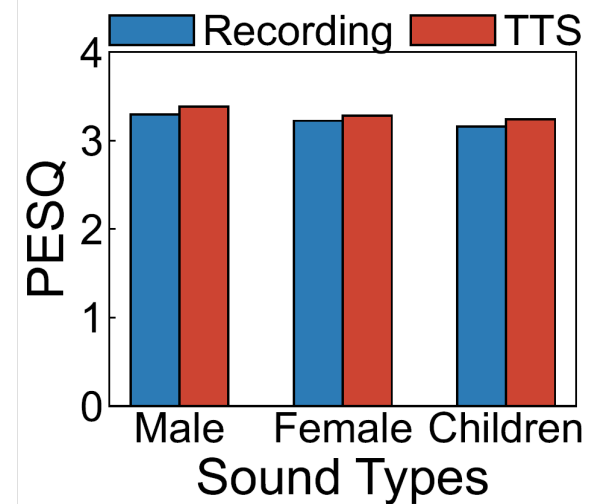
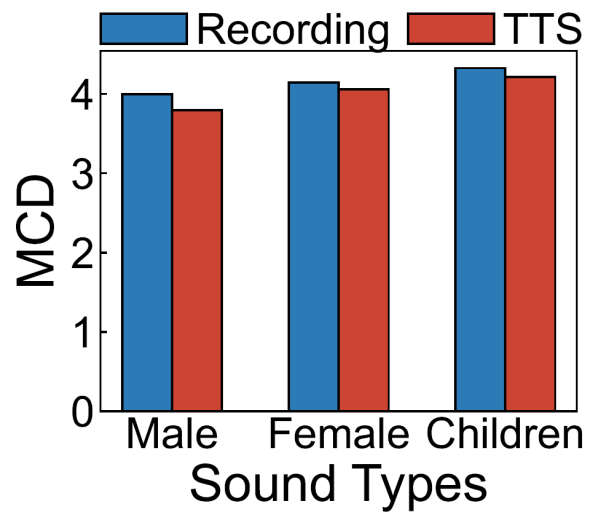
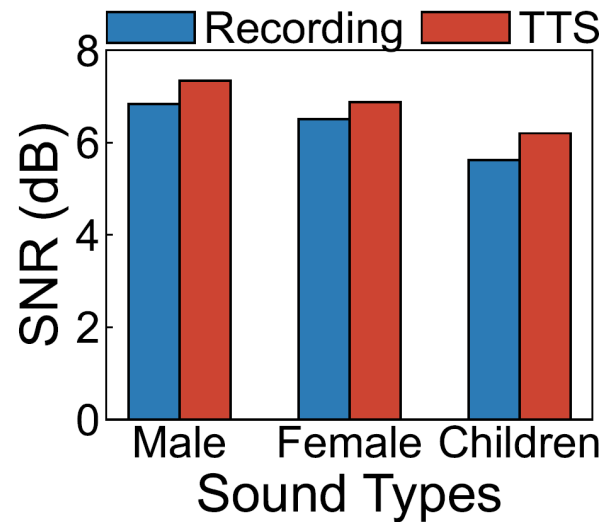
# Impact of Environment



**Our system can work well in both indoor and outdoor environment**



# Impact of Sound Types



**Our system can work well for all sound types**

