

MobiCom 2024

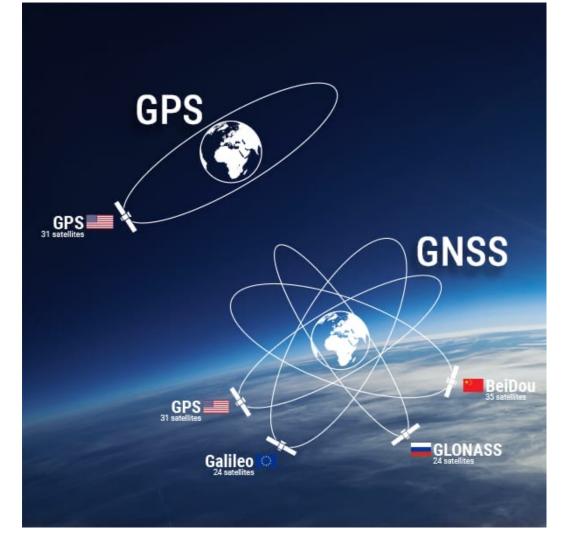


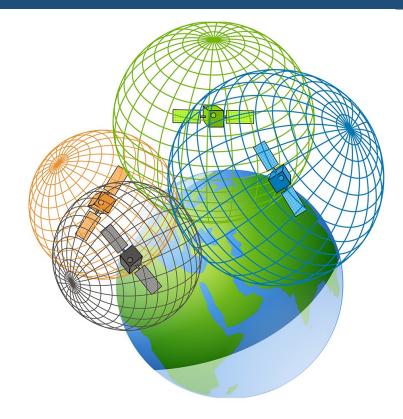
GPMS: Enabling Indoor GNSS Positioning using Passive Metasurfaces

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Global Navigation Satellite System (GNSS)

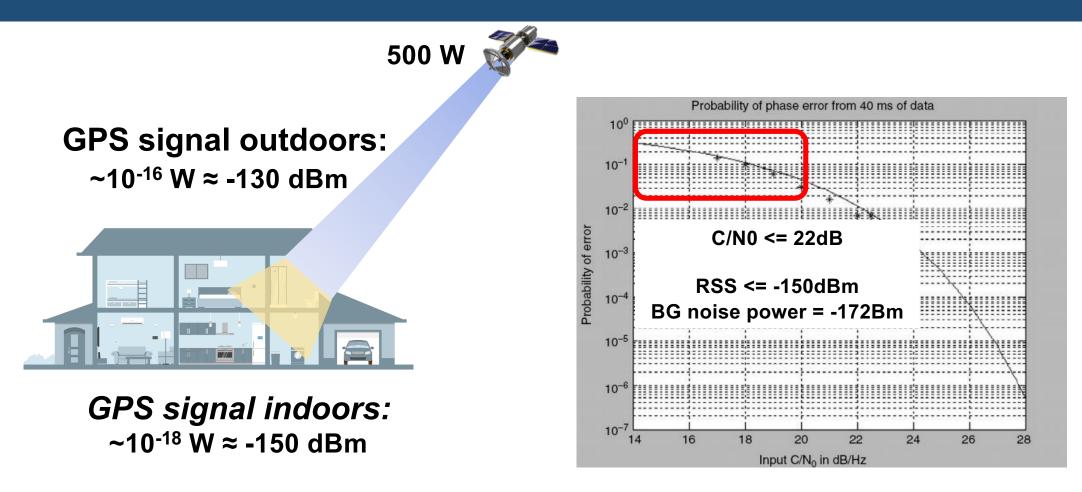




4 satellites -> (X,Y, Z, T)

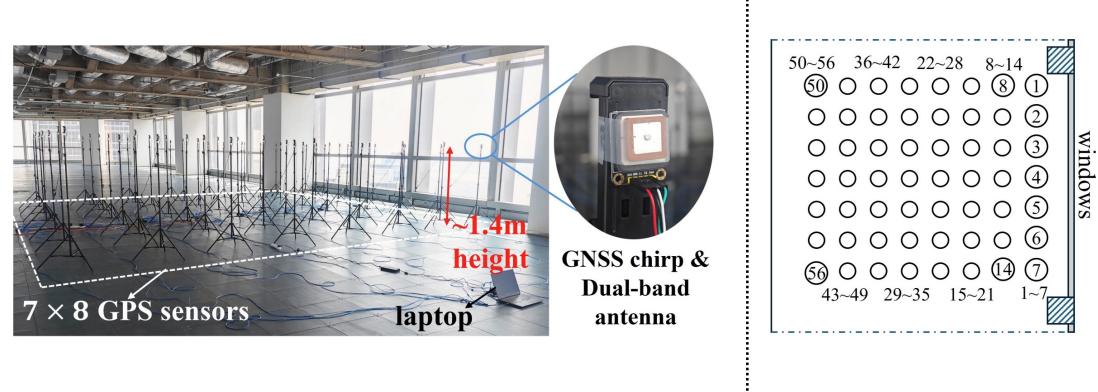
Localization error (outdoor) ~1 meter

When GNSS comes to indoors



We CANNOT decode GNSS signals with such a low signal strength indoor.

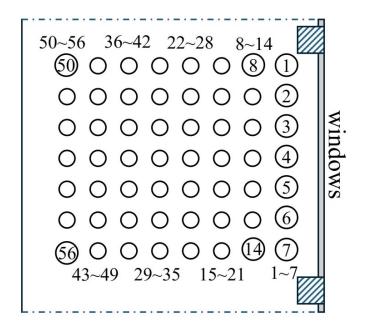
Indoor GNSS measurements

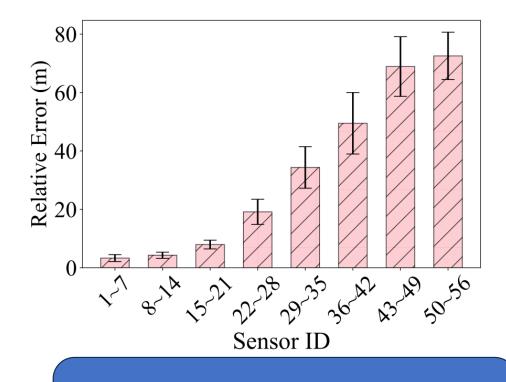


Top view

Real-world measurement setup

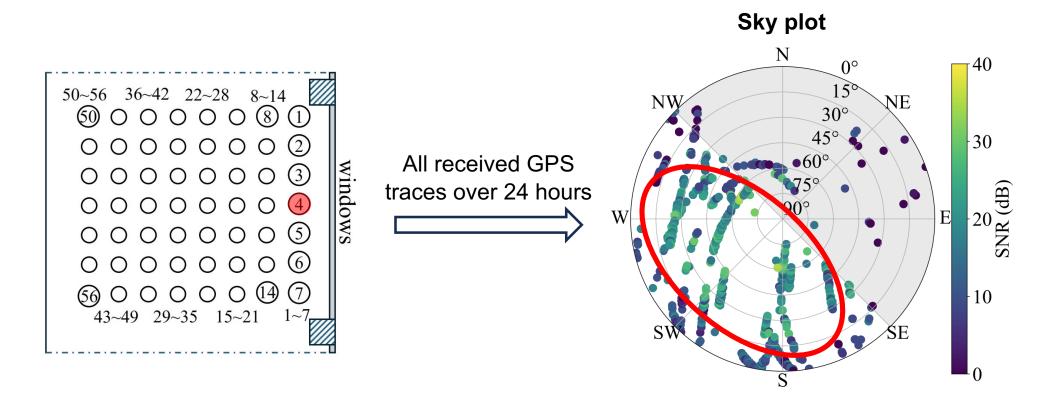
Indoor GNSS measurements





The closer to the window, the smaller the positioning error

Indoor GNSS measurements



At the position near the window, the greater the angle of incidence, the greater the SNR of the received signal.

Why low SNR of GNSS signals indoors



Two mainly reasons:

Can we make GNSS serve for indoor positioning?



Shopping mall (indoor environment)

2. Severe attenuation of GNSS signals by walls

Our idea: Design passive metasurface to enhance GNSS signals indoors

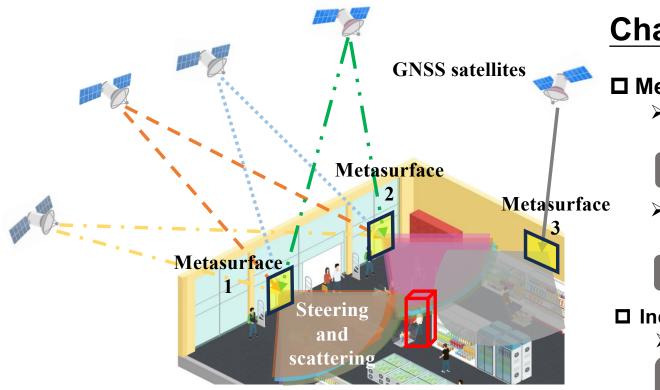


Shopping mall (indoor environment)



- Easy to deploy
- **Cheap** (martial cost of metasurface< \$5/m^2)

Our idea: Effective steering and scattering



Deploy metasurfaces on the windows and walls

Challenges:

- □ Metasurface design
 - GNSS satellites are moving, and have different incident angles

Powerful steering for any incident angles

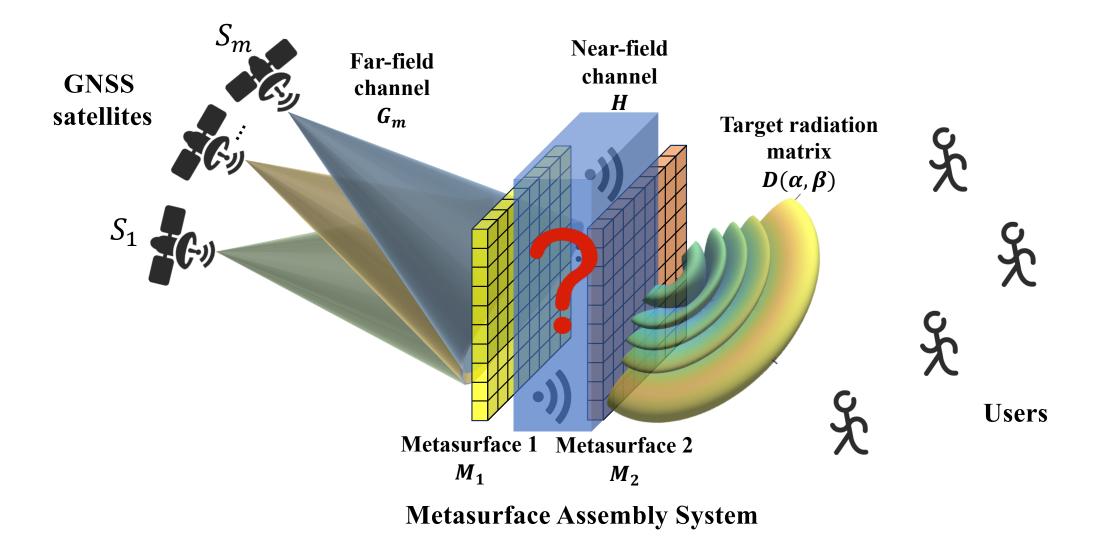
Indoor users are also moving and everywhere

Powerful scattering for maximum coverage

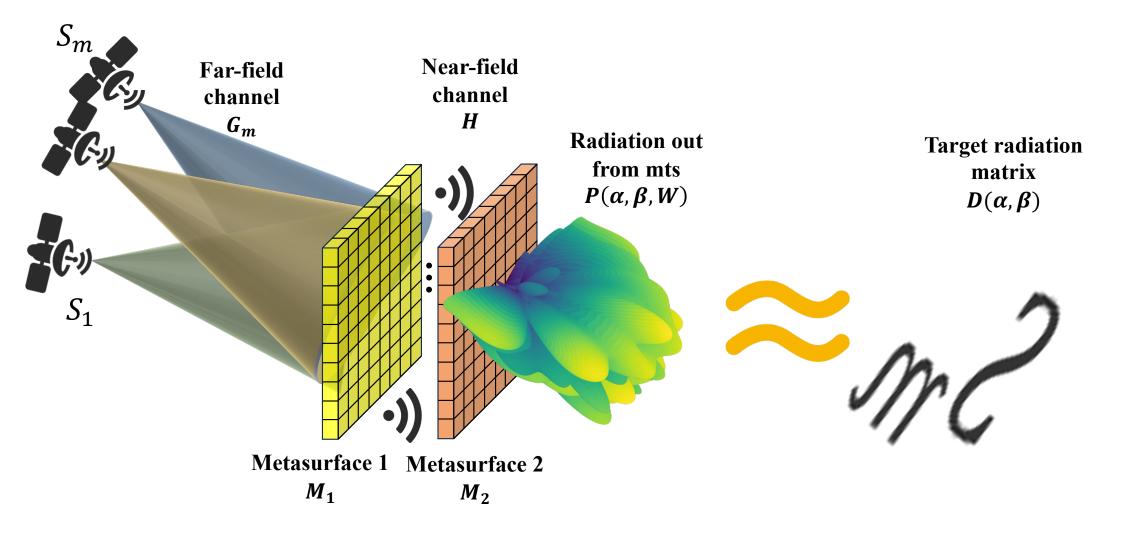
Indoor positioning algorithm design Satellite -> mts -> user

Novel indoor positioning compatible with deployed metasurfaces

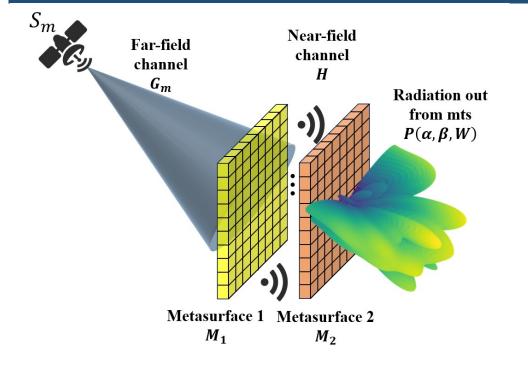
Macroscopic: Metasurface design (phase map) for GNSS



Macroscopic: Metasurface design (phase map) for GNSS



Macroscopic: Metasurface optimization model



Element weights radiated out from metasurface 2:

$$W = G_m M_1 H M_2$$

Radiation pattern radiated out from metasurface 2:

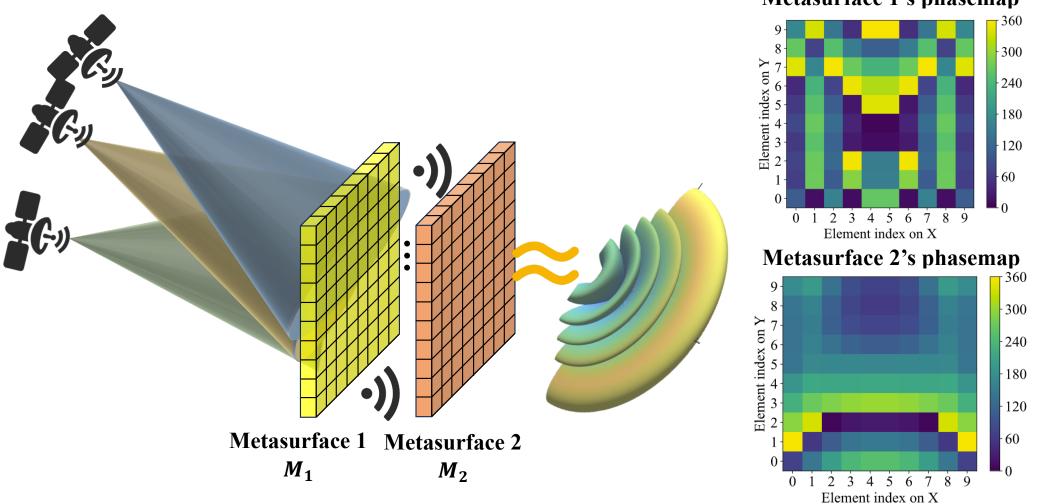
$$P(\alpha, \beta, W) = \frac{AF(\alpha, \beta, W)}{max(AF(\alpha, \beta, W))}$$

where $AF(\alpha, \beta) = \sum_{i=1}^{N} \sum_{j=1}^{N} w_{i,j} \cdot e^{-j\left(2\pi \frac{d_x}{\lambda}(i-1)\sin\alpha\cos\beta + 2\pi \frac{d_y}{\lambda}(j-1)\sin\beta\right)}$

Optimization Problem: for all GNSS satellite signals, we determine the optimal M_1 and M_2 to make the radiation patterns from the metasurfaces close to the target radiation pattern.

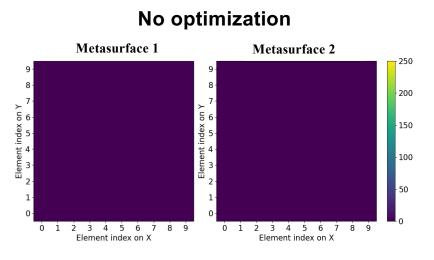
$$\min\sum_{m=1}^{K}\iint (P(\boldsymbol{\alpha},\boldsymbol{\beta},\boldsymbol{W}) - D(\boldsymbol{\alpha},\boldsymbol{\beta}))^{2}d\alpha d\beta$$

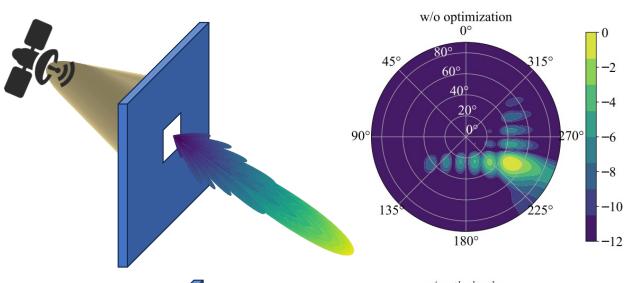
Optimized metasurface design

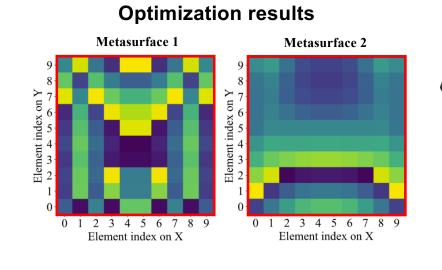


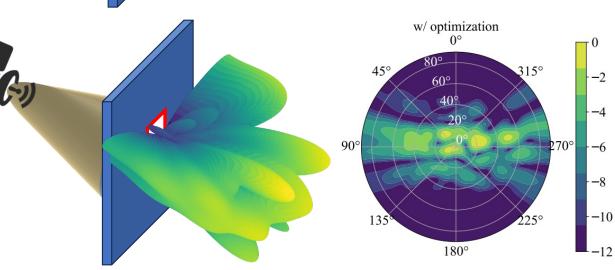
Metasurface 1's phasemap

Comparison of not using optimized mts vs. using optimized mts

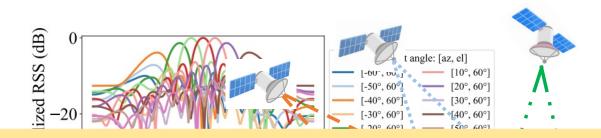




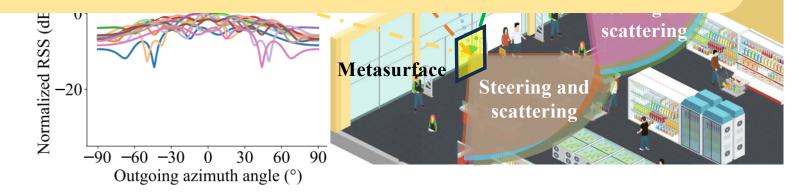




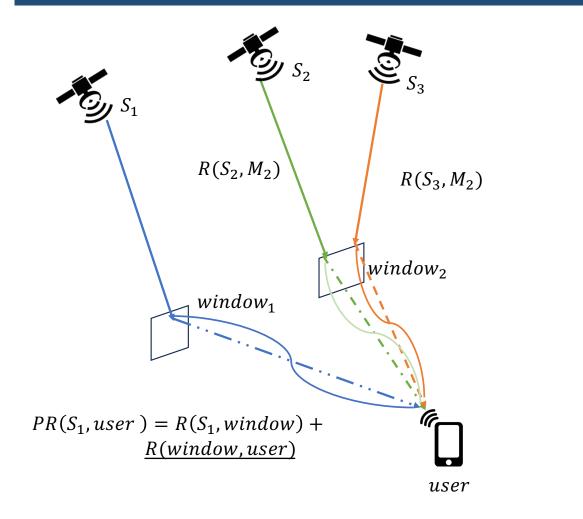
Simulation: scattering and steering performance

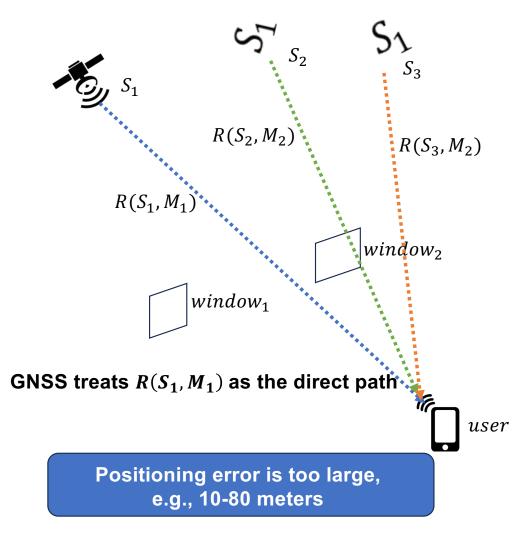


How to design an indoor positioning algorithm that is COMPATIBLE with metasurfaces?

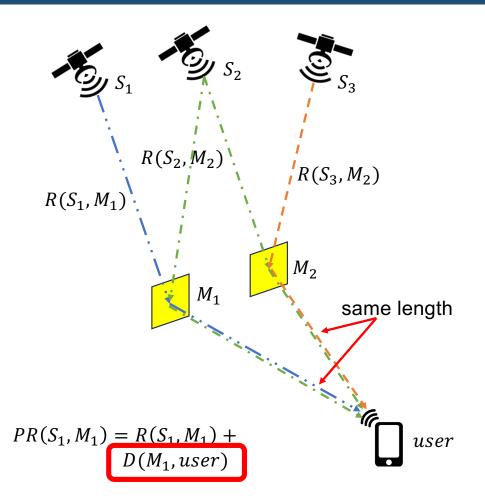


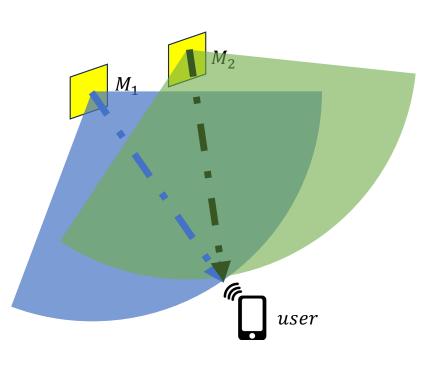
GNSS-based Indoor Positioning



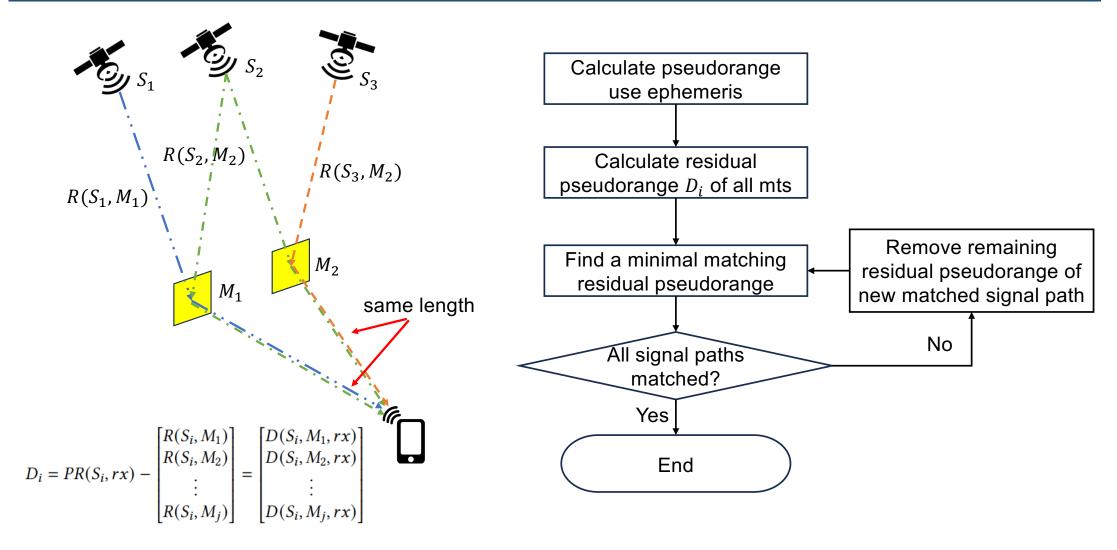


GNSS-based Indoor Positioning with Metasurfaces

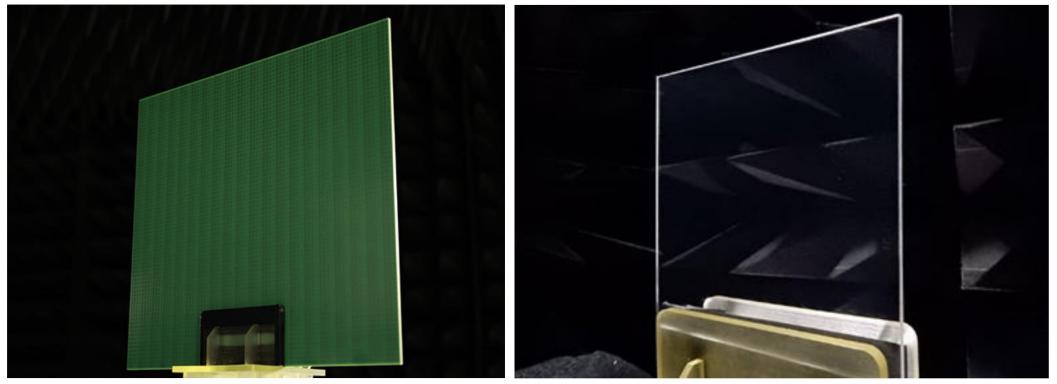




GNSS-based Indoor Positioning Alg. with Metasurfaces



Experiment Setup and Metasurface Fabrication

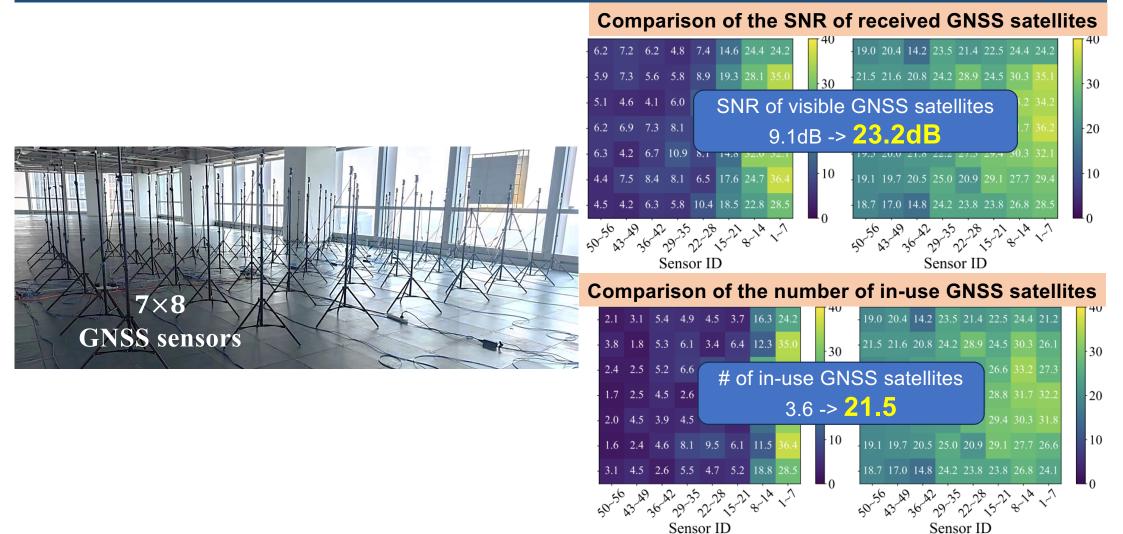


Transmissive Metasurface (Prototype)

Transparent Transmissive Metasurface (Prototype)

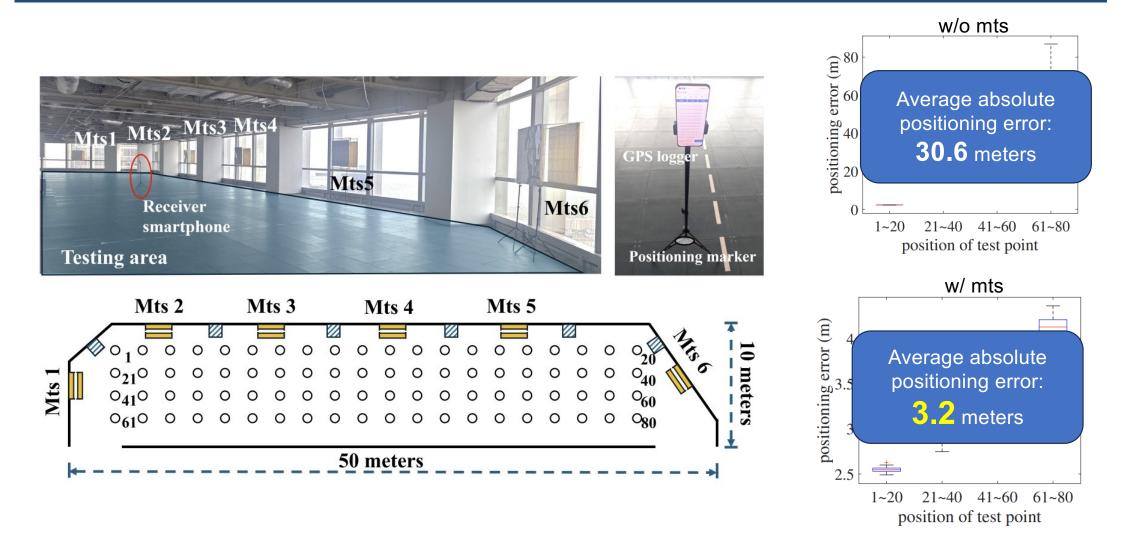
https://global.kyocera.com/newsroom/news/2022/000526.html

Metasurface performance on indoor coverage



Sensor ID

Indoor positioning performance





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Thanks for listening!